

# Mobile Computing & Sensing

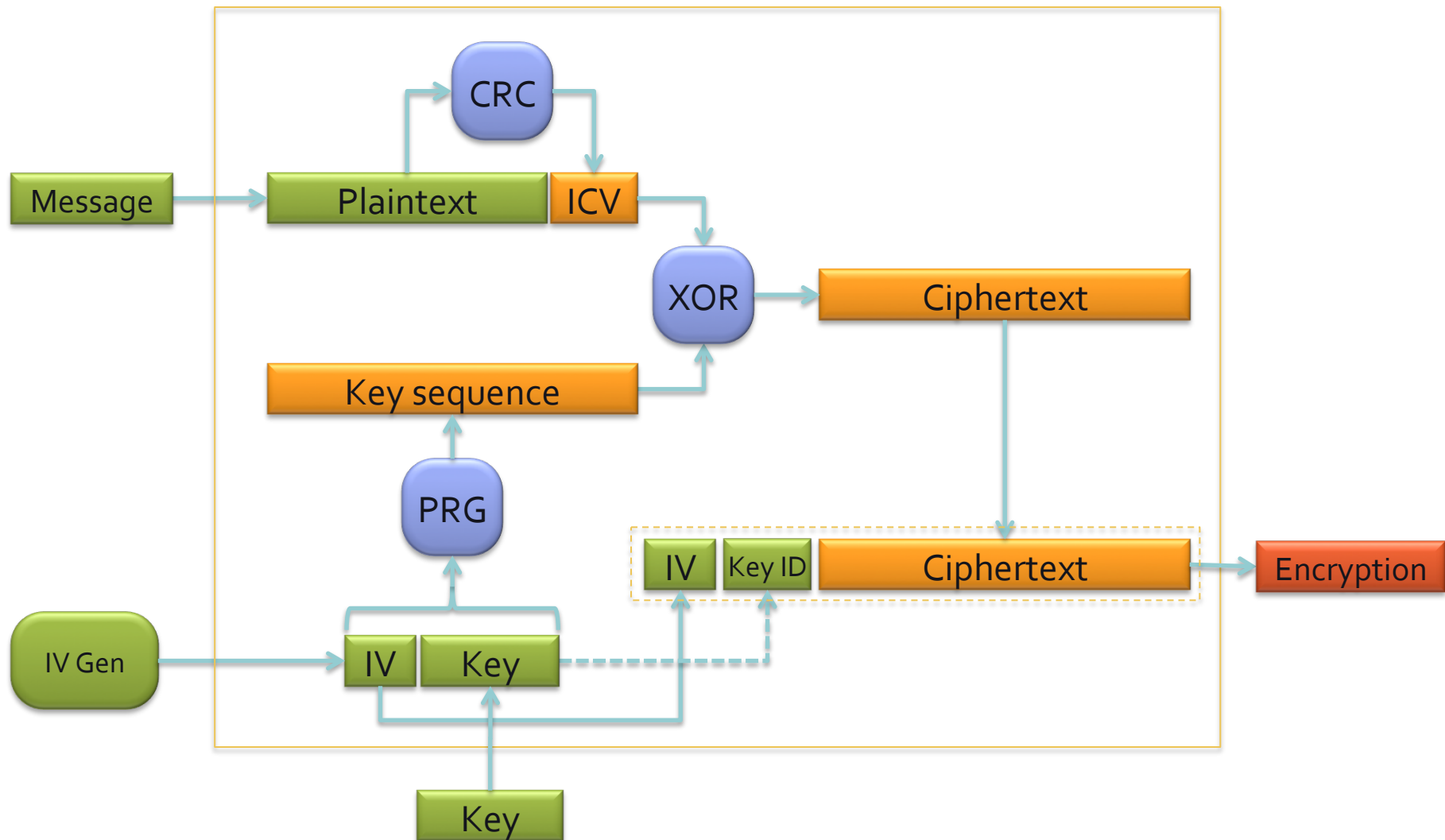
Mobile Computing

Minho Shin

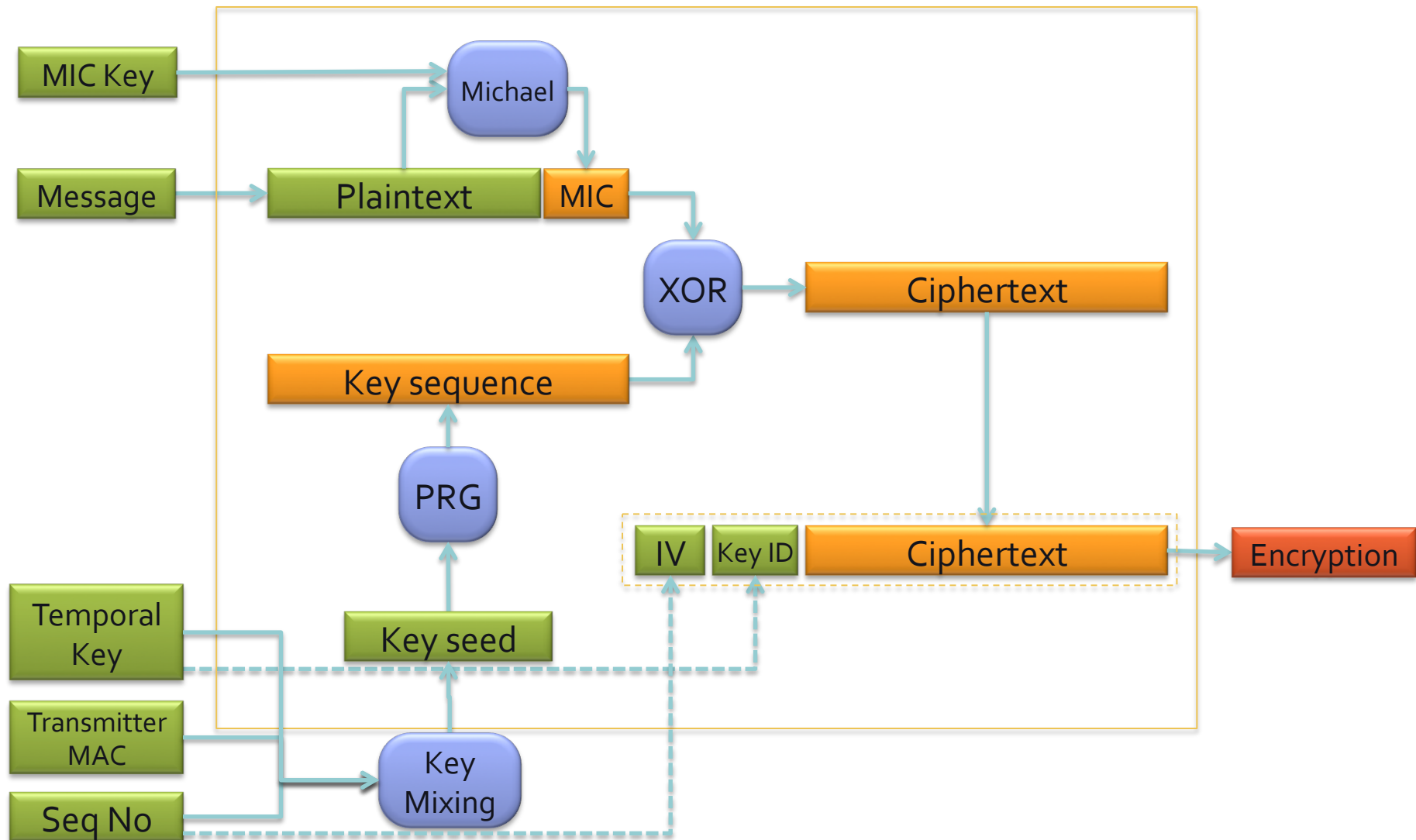
2012. 9

# **REVIEW: WLAN SECURITY**

# WEP: RC4



# Enc/Dec of TKIP





# Why WEP is not secure?

- Authentication
  - Non-mutual authentication
  - Key streams are revealed with corresponding IVs
- Integrity
  - Flipping & CRC analysis allows modification
- Confidentiality
  - Frequent IV reuse reveals plaintext
  - Direct key attack possible

# Quiz

- Explain how the RC<sub>4</sub> algorithm in WEP encrypts and decrypts a frame

# Quiz

- Why WEP is considered insecure in three aspects of security?



OUTPUT



# Goals of Mobile Sensing

- Personal sensing
  - Provide services that are best for given personal context
- Large-scale sensing
  - Provide aggregate information based on a large number of user contexts

# What to sense?

- About Environment
  - Air pollution
  - Noise Level
  - Brightness
  - Weather
  - Traffic
  - Near-by stores
- About the user
  - Location, Place
  - Activity
  - Social surroundings
  - Intention
  - Transportation
  - Emotion
  - Health

# What is a sensor?

- A sensor is a (physical) device for detecting and signaling a changing condition
- Changing condition:
  - Discrete sensing: the presence or absence of an object or material
  - Analog sensing: It can also be a measurable quantity like a change in distance, size or color



# Pervasive Sensing



*Spanish Steps, Rome, Italy*



# Pervasive Sensing

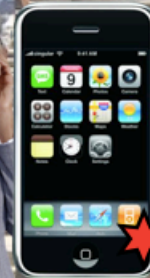


80° F

*Spanish Steps, Rome, Italy*



# Pervasive Sensing



80° F

Standing

*Spanish Steps, Rome, Italy*



# Pervasive Sensing

Rome

80° F

Standing

*Spanish Steps, Rome, Italy*





Pervasive  
Sensing

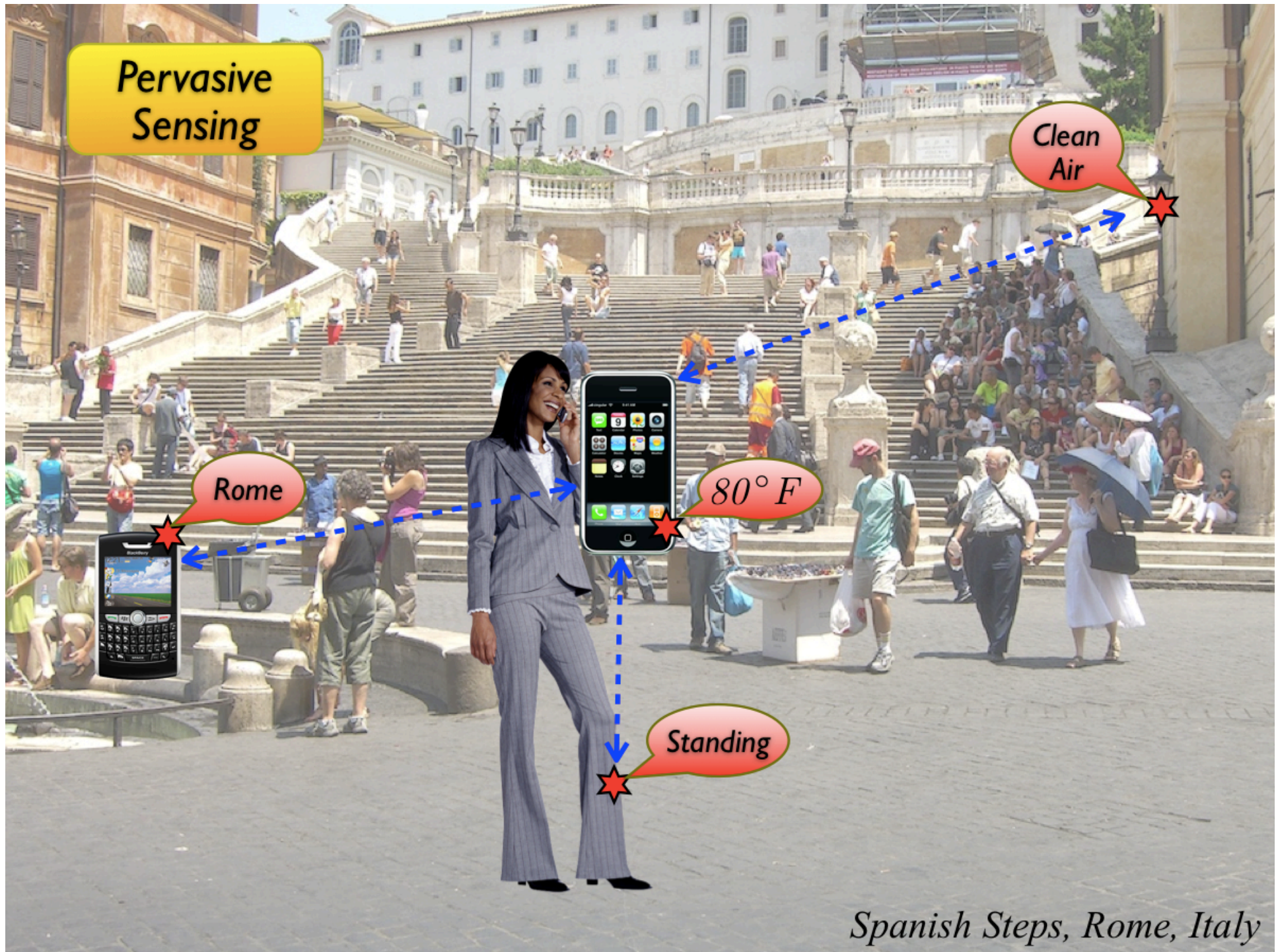
Clean  
Air

Rome

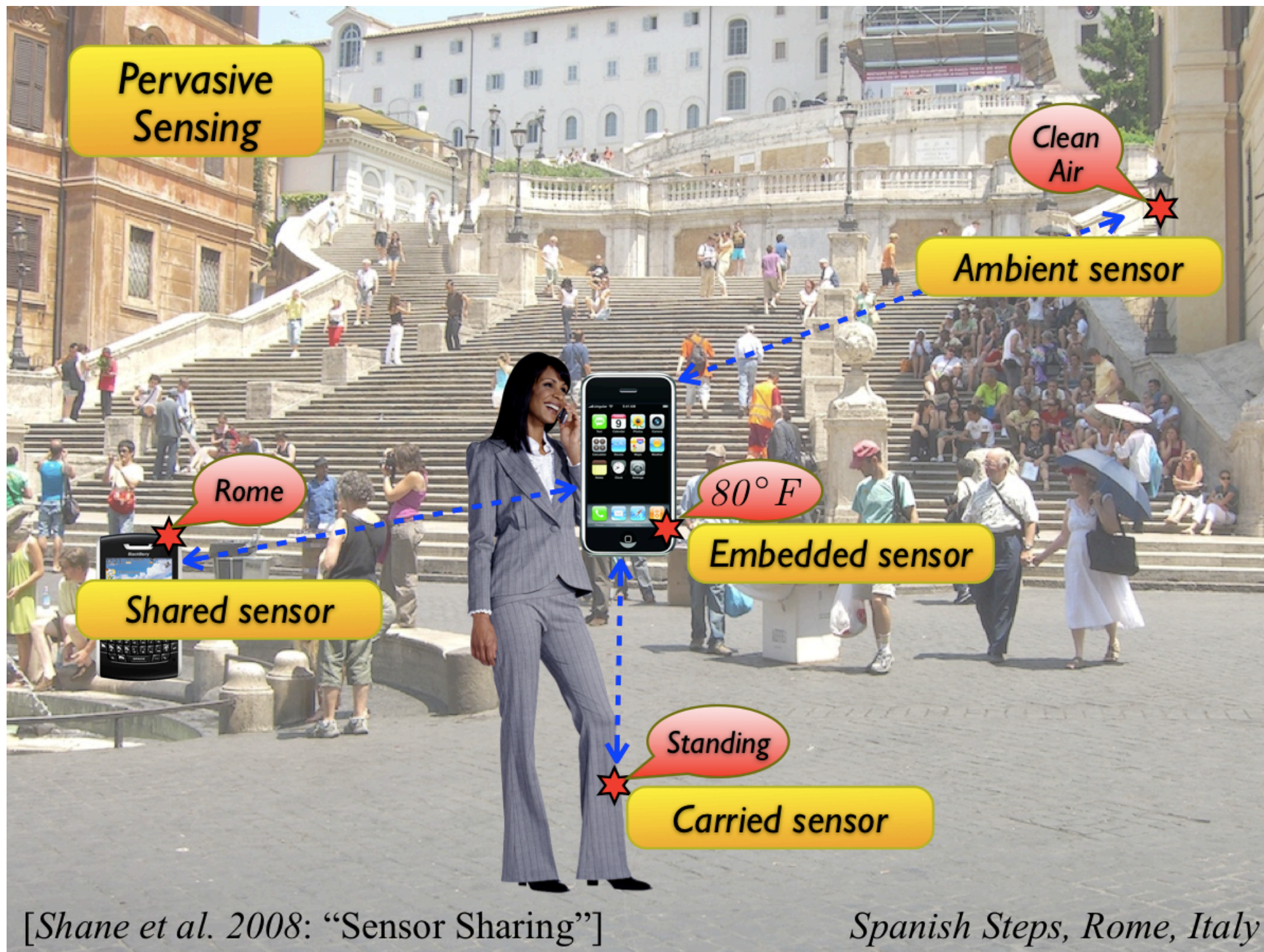
80° F

Standing

*Spanish Steps, Rome, Italy*







# Types of Sensors: by Location

- Embedded Sensor
  - Enclosed within the mobile device
- Carried Sensor
  - Attached to the body
- Shared Sensor
  - Shared by a near-by user (embedded or carried)
- Ambient Sensor
  - Installed on infrastructure

# Virtual Sensor

- A virtual sensor is a software component for detecting and signaling a changing condition
  - from Information server
  - from PIMS (Personal Info. Management System)
  - Semantic Information

# Sensor Modality

- Types of changing condition being sensed
- Smartphone embedded sensors
  - GPS
  - Accelerometer
  - Gyroscope
  - Light sensor
  - Proximity
  - Microphone
  - Camera
  - WiFi interface
  - Bluetooth interface



# Sensor Modality

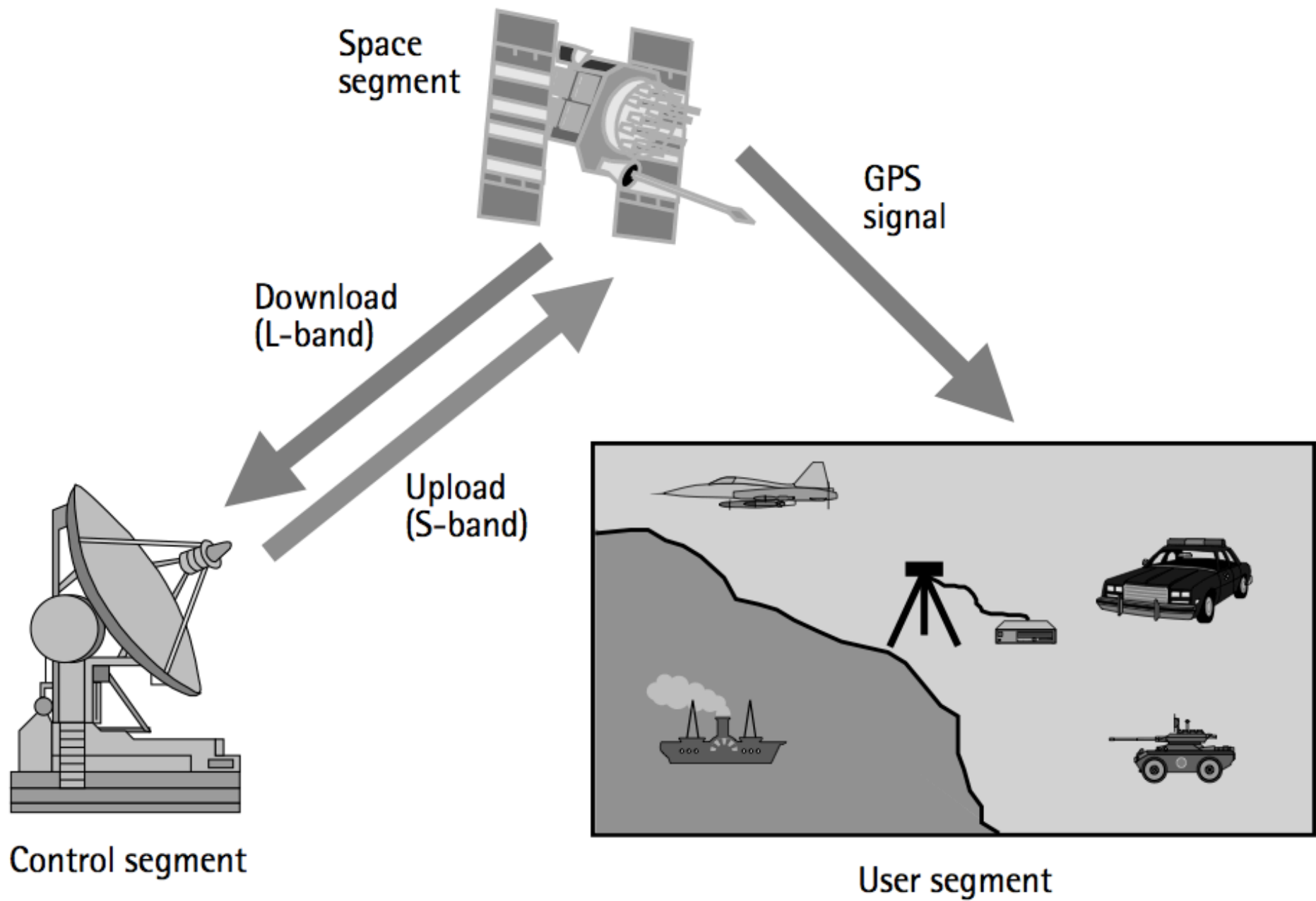
- Attached/ Installed sensors
- Environment
  - Temperature
  - Humid
  - Air pressure
  - Air pollution
- Medical
  - ECG (Electrocardiography)
  - EEG (Electroencephalograph)
  - Heart rate
  - GSR (Galvanic Skin Response)

# GPS: History

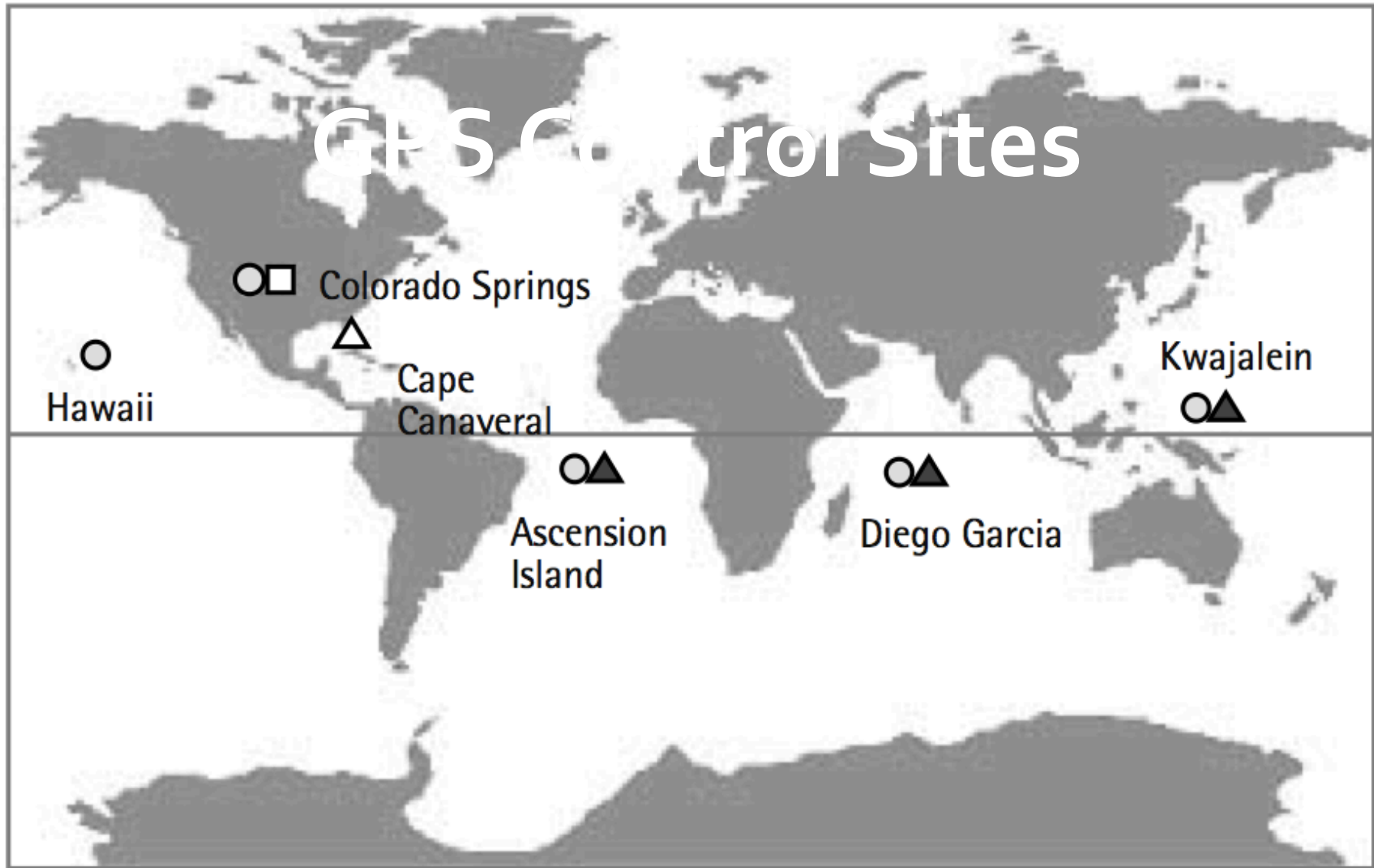
- NAVSTAR (Navigation Satellite Timing and Ranging) Global Positioning System (GPS) is a satellite-based navigation system
- Developed by the U.S. Department of Defense (DoD) in the early 1970s as a military system
- Later made available to civilians
- Now a dual-use system that can be accessed by both military and civilian users

# GPS overview

- Services:
  - Location (X,Y,Z) & Time
  - Velocity
- Any- where in the world under any weather conditions.
- Serves an unlimited number of users
- Accuracy
  - 22m (95%) for single receiver
  - a few meters with two receivers (differential method)



# GPS Control Sites

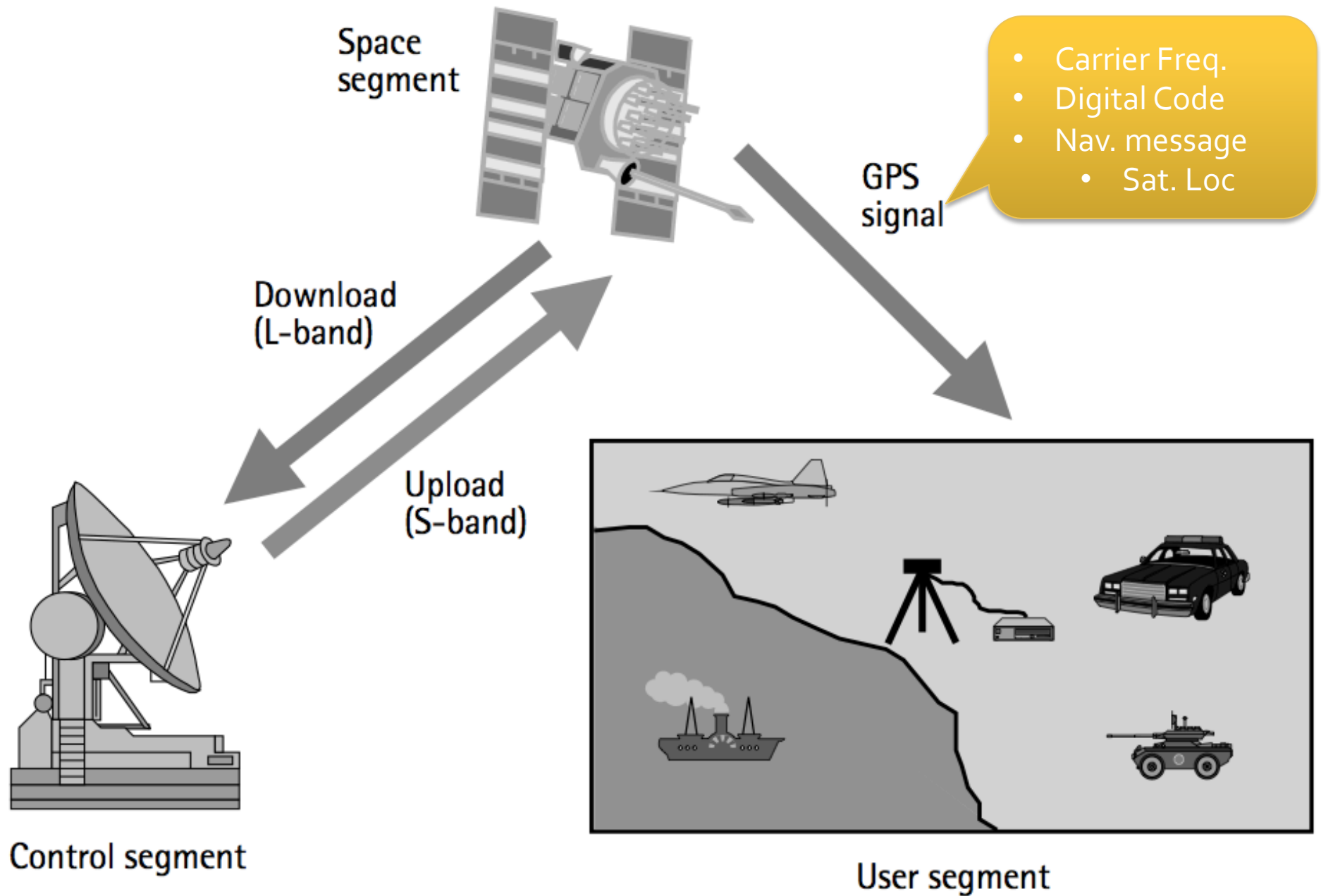


□ Master control station

○ Monitor station

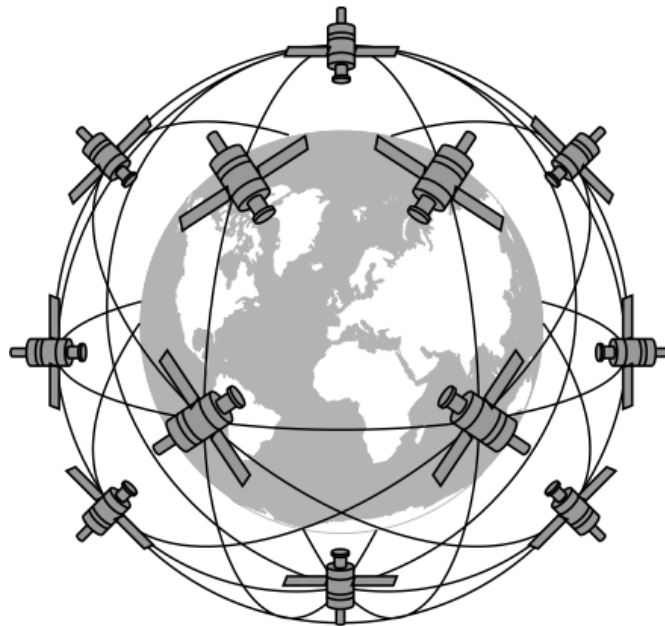
▲ Ground antenna

△ Backup ground antenna



# GPS satellites (1)

- GPS consists of 24 satellites (29 currently), orbiting 12,000 miles above at 7,000 miles/h, taking 12 hrs to circle the earth
- 4-10 satellites are visible anywhere in the world



# GPS satellites (2)

- Computer: controls its flight and other functions.
- Atomic clock: accurate time within three nanoseconds
- Radio transmitter: sends signals to Earth
- NUDET Sensor (NUclear DETonation):
  - detect nuclear-weapon explosions, assess the threat of nuclear attack, and help evaluate nuclear strike damage.
- Solar-powered, lasting for around 10 years



# Types of GPS signal

## C/A-code

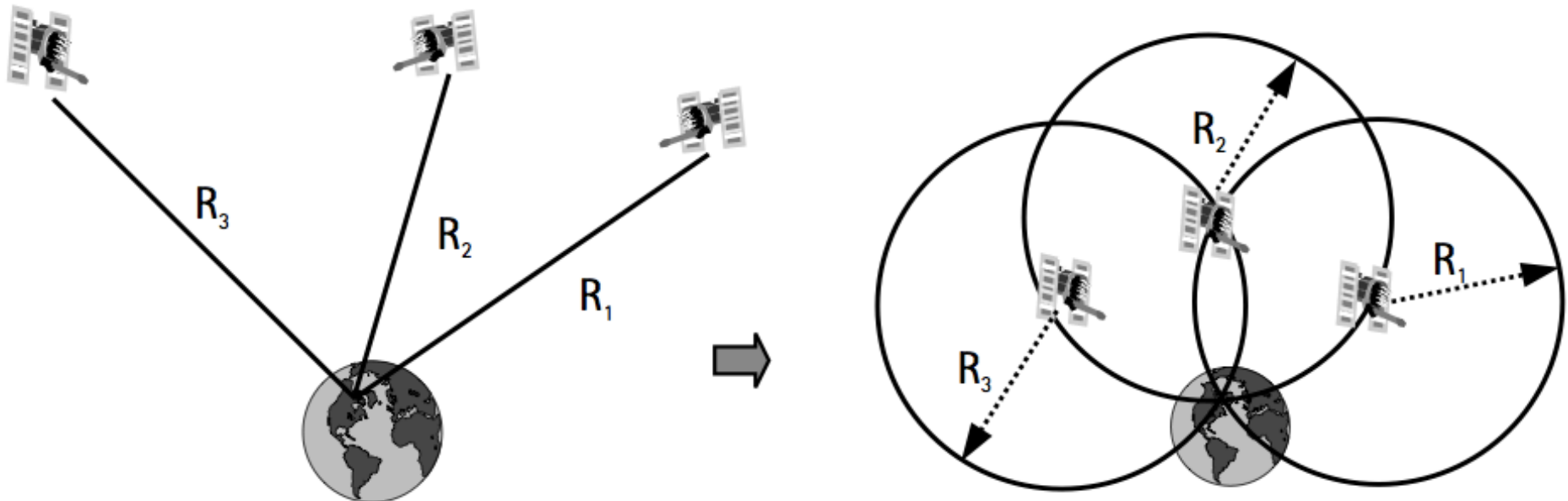
- Coarse Acquisition code
- SPS (Standard Positioning Service) at 1575.42MHz
- Less accurate
- Easier to jam and spoof
- Quick to acquire position
- Consumer GPS units
- 100m (now 22m)

## P-code

- Precision code
- PPS (Precise Positioning Service) at 1227.6 MHz.
- Highly precise
- Difficult to jam and spoof.
- Encrypted
- The U.S. military only
- 16m

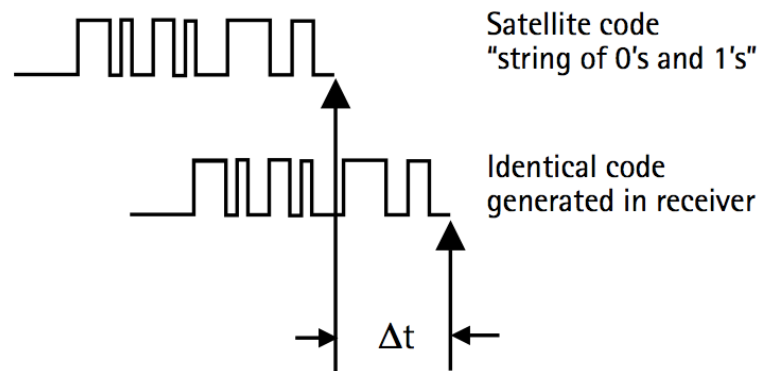
# How GPS works?

- Given distances of three (or more) satellites and their locations, calculate my position
  - Location: from the Navigation Message

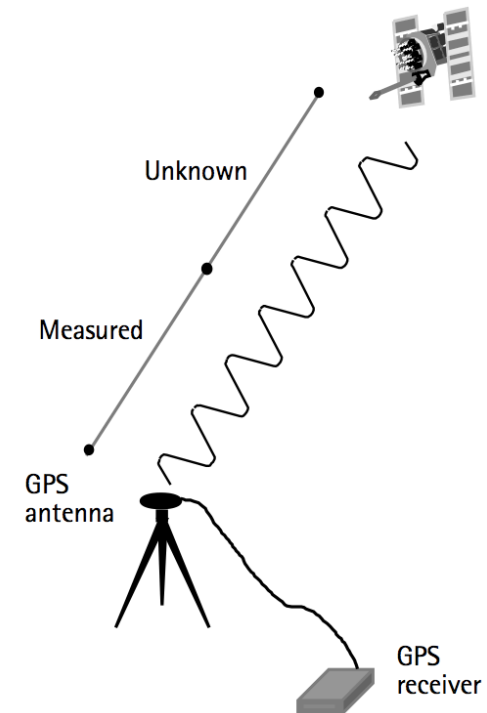


# Distance Measurement

- Pseudorange measurement



- Carrier-phase measurement



# GPS data

- Time: time information from atomic clocks
- Location:
  - Latitude (x coordinate)
  - Longitude (y coordinate)
  - Elevation
- Speed: your moving speed.
- Direction of travel: direction of travel if you're moving.

# Application of GPS data

- Raw
  - Position: LBS (Location-based Services)
  - Speed: Traffic monitoring
  - Time
- Processed
  - Mobility trace
  - Significant places analysis

# GPS: Pros & Cons

- Pros:
  - Free of service
  - Fairly accurate
- Cons
  - Energy starving
  - Outdoor only
  - No semantics